INJORA | T4DCM

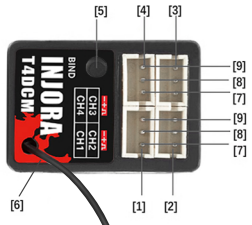
Quick Start Guide

Specification

Size：21.5*14.5*6.8mm
Weight：2.3g
Voltage Range：4.8-10V
Servo Interface：ZH1.5
Range：350 meters
Servo Mode：digital / analog

Wireless Frequency：2.4GHz
Signal：PWM*4
Spread Spectrum：FHSS
Applicable：car, ship, tank, robot
Compatibility：T6 / T6M

Interface Description



[1] CH1
[2] CH2
[3] CH3
[4] CH4
[5] Binding button

[6] Antenna
[7] Signal
[8] VCC
[9] GND

Binding

Put the transmitter and the receiver close to each other (about 50 centimeters) and power both on. Long press the binding button for more than 3 second and then release, the LED will flash quickly, indicating that the binding is ongoing; When the LED stops flashing and is always on, binding is complete . If not successful, the LED will keep flashing slowly to notify, and repeat the above steps.

***Note**: The close distance between the transmitter and receiver may cause a signal block, which leads to unsuccessful binding or signal loss. After the binding is successful, if the transmitter and receiver are too close, the signal may also be lost because of signal block. Bring the transmitter and receiver farther apart, the signal loss will resume automatically.

Failsafe

Short press the binding button and the indicator will blink quickly, indicating that you have entered the failsafe setting. Set the channel that needs to set failsafe to the desired position, keep the state of the channel unchanged, press the binding button again, the indicator will be on, save the setting and exit.

Servo Mode Setting

Short press the binding button 4 times, to switch the servo signal output between digital and analog. When the servo signal output from the receiver is not correct for the servo model, the servo will emit a“squeaky squeaky" sound, vibrate and become hot. At this time you need to switch the servo mode.

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